

Bowling Assistant

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Mechatronics
Circus &
Mechatronics
Symposium 2020



Aalto-yliopisto
Aalto-universitetet
Aalto University

Sampo Laine
Topias Turunen
Martin Guggemos

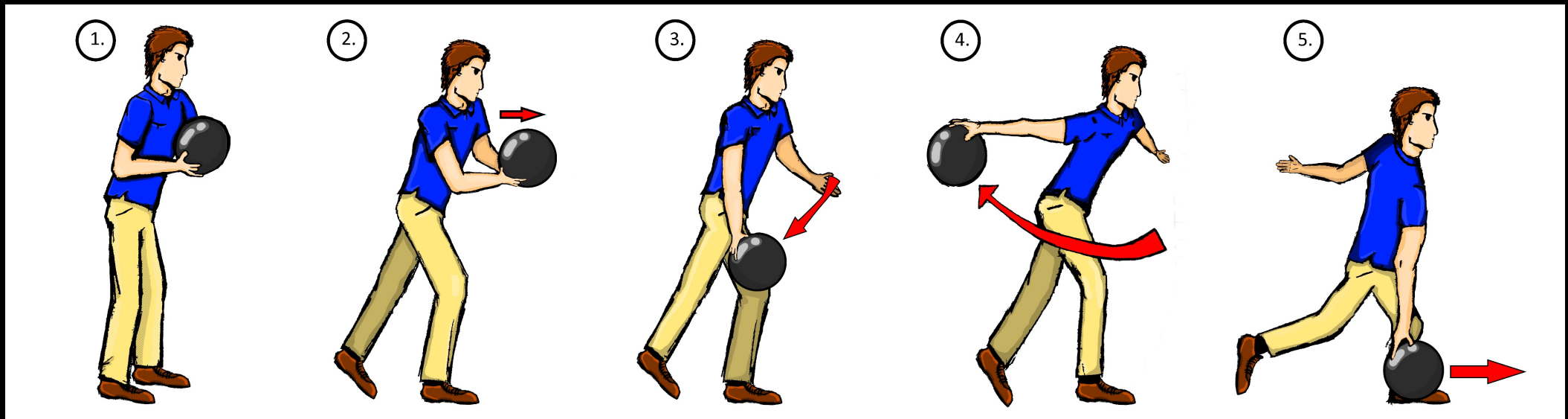


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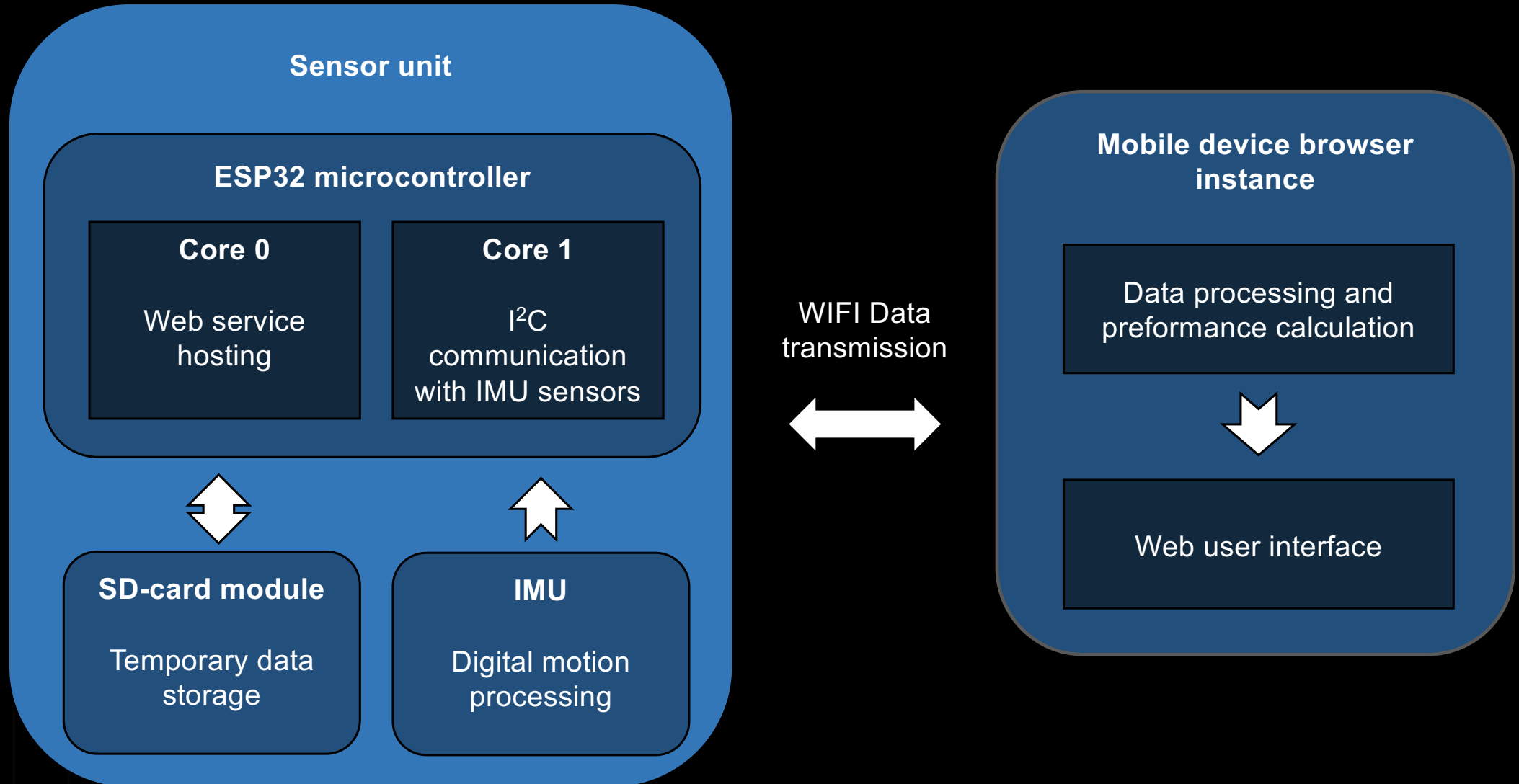
- How do we tell a good bowling performance? – Key points
- How does the system work? – IMU, Sensor fusion
- How do you receive feedback? – Web Interface
- How precise is the system? – Reference device, Validation
- What is the takeaway? - Discussion

Some key aspects in bowling

- Swing plane
- Step timings
- Ball-Ankle distance



The application concept



Sensor unit

ESP32 microcontroller

Core 0

Web service
hosting

Core 1

I²C
communication
with IMU sensors



SD-card module

Temporary data
storage



IMU

Digital motion
processing

WIFI Data
transmission



Mobile device browser instance

Data processing and
preformance calculation



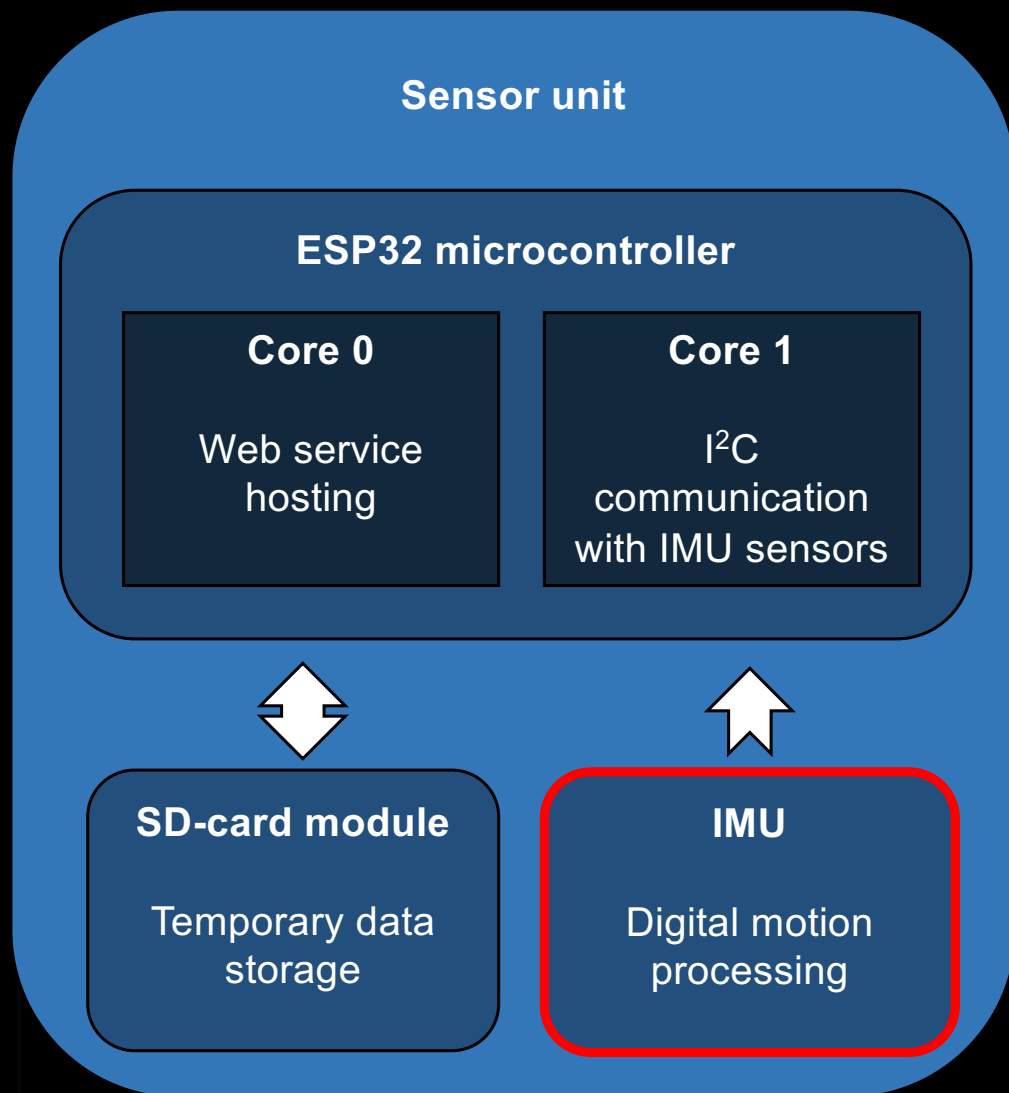
Web user interface

Wearable Sensor unit

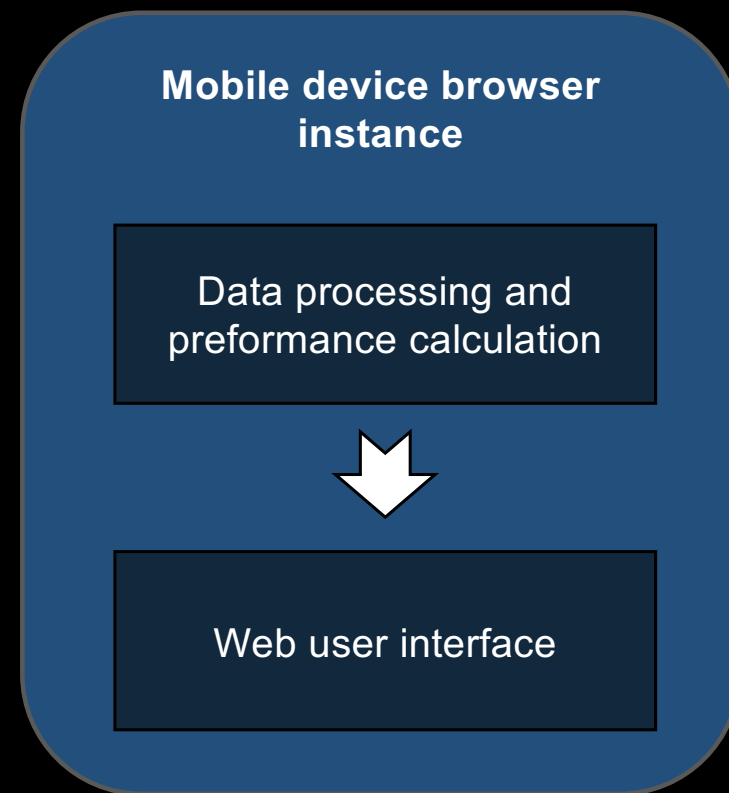
Features:

- Components hidden inside small casing
- Wireless measurement
- Modular design allows for multiple configurations

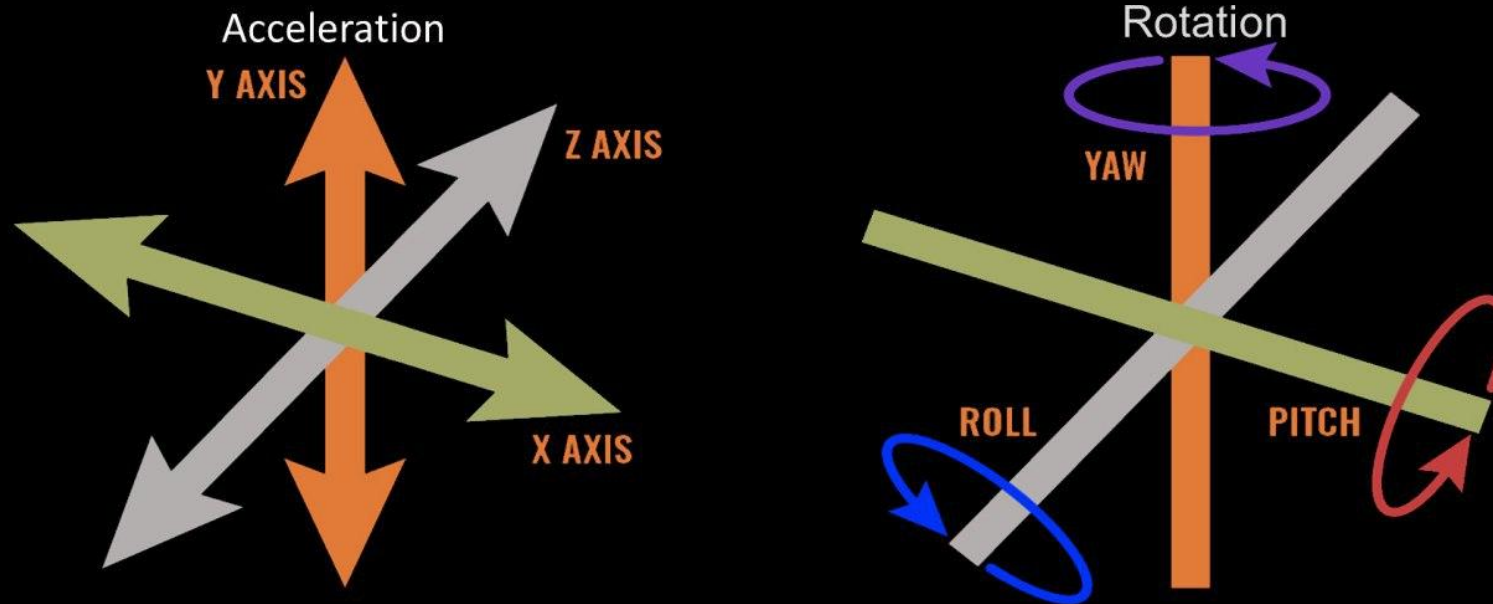




WIFI Data transmission



Inertial Measurement Unit

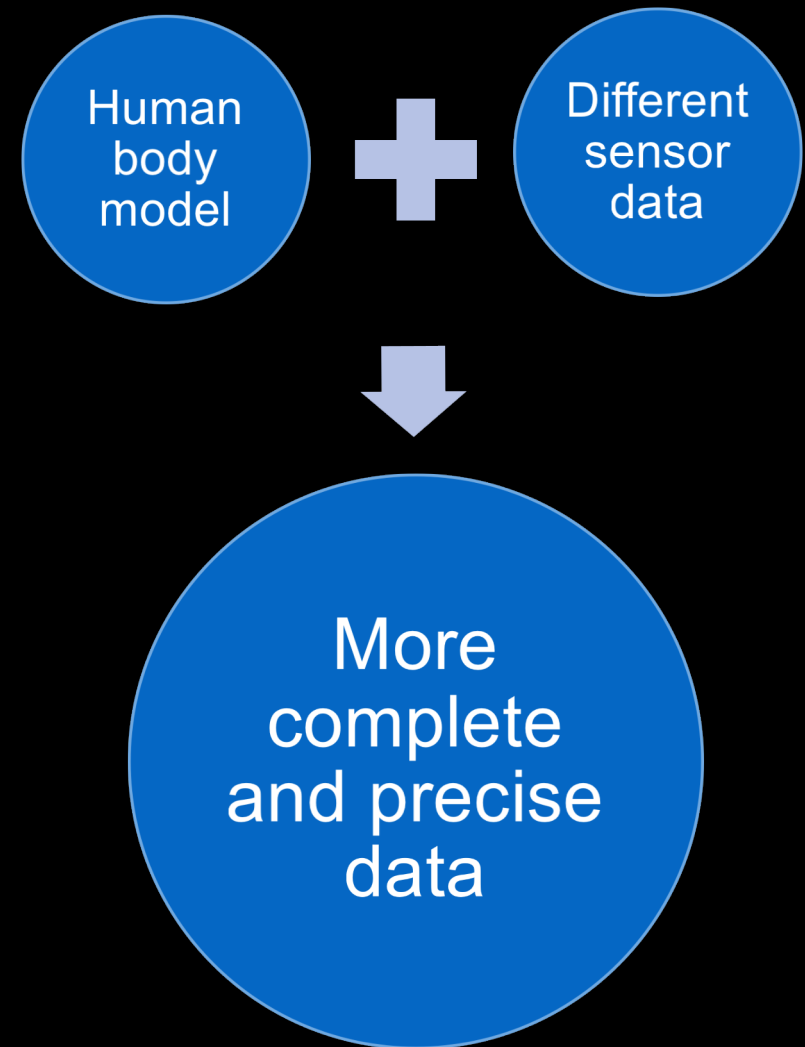


Things to worry about:

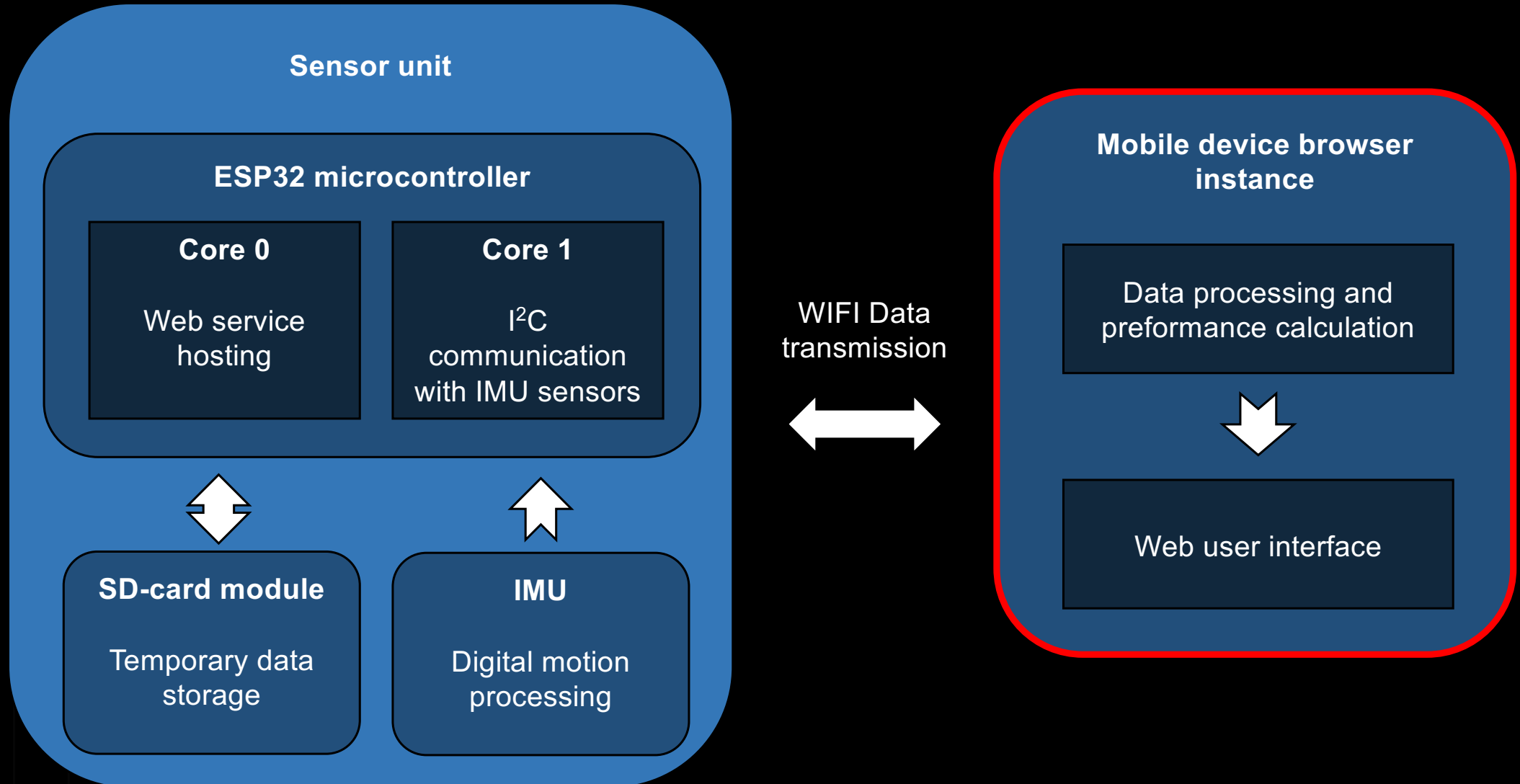
- Multiple sources of data
- Signal drifting
- Data accuracy

Sensor fusion

- The measurement data of from one sensor is insufficient to measure the orientation of the human body
- Combination of multiple sources of data is required



The application concept



User Interface

Instant feedback

- Web user interface
- Performance consuming calculations can be done on the mobile device
- Data from bowling the performance is presented
- Multiple attempts can be stored

Bowling assistant concept

Latest shot

Step timing: 30 ms

Swing: 15 deg

Ankle distance: 20 cm

Release speed: 15 m/s

Measurement time: 4 s

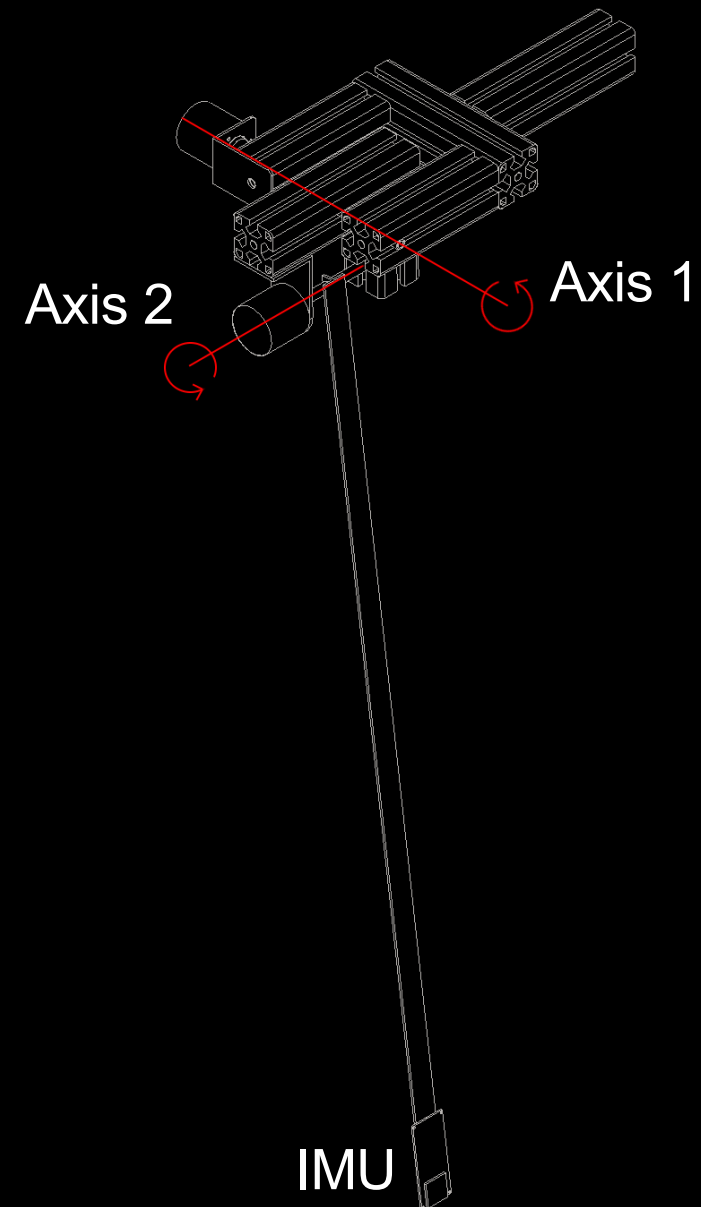
Start measurement

Start

Stop

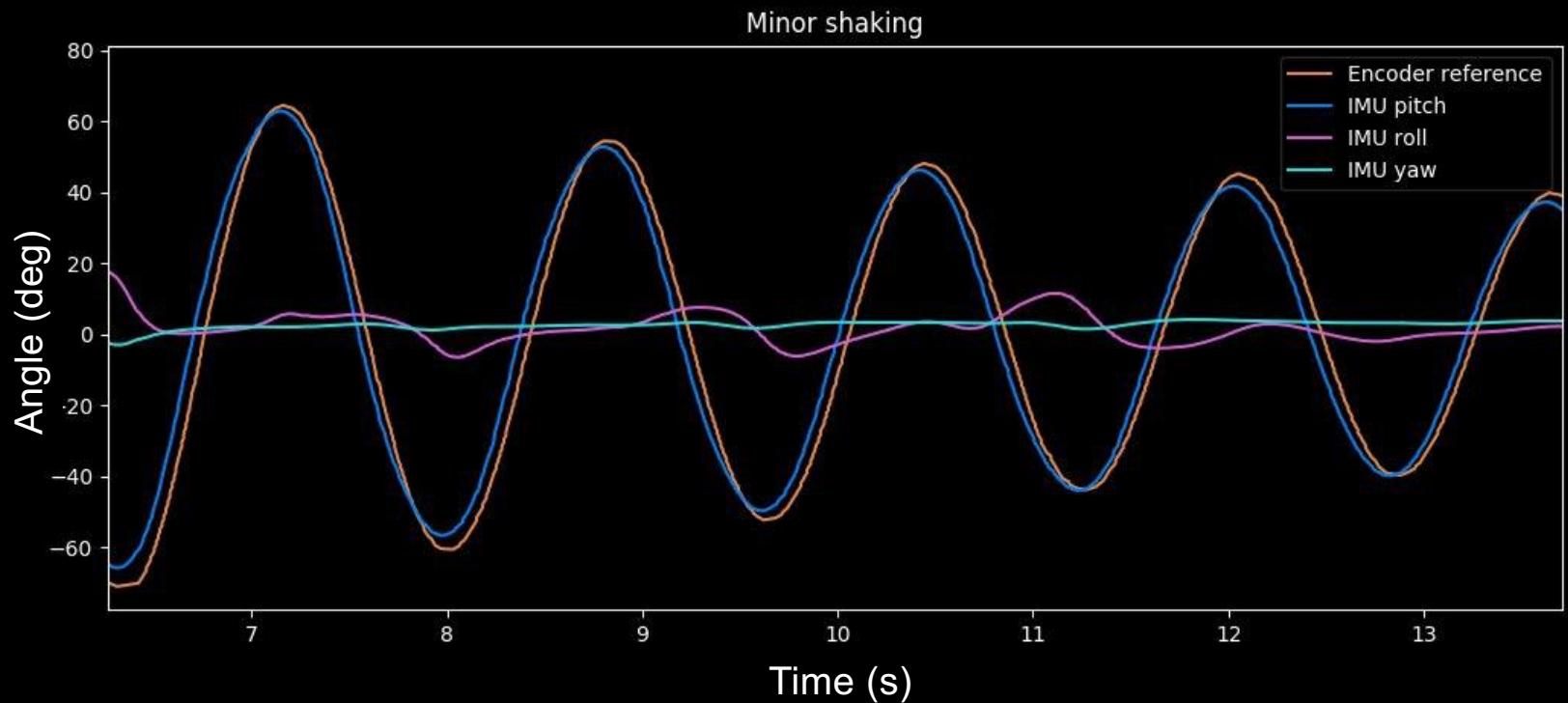
Reference Device

- Two degrees of freedom pendulum resembling the elbow joint of a person
- Two rotary encoders capture the reference position



Validation measurements

- Comparison between encoder and IMU rotation data shows good correlation



Discussion

- The system is accurate enough to determine the movement of a human body
- Various performance characteristics can be extracted
- Accurate feedback can be given to user
- More motion tracking use-cases are conceivable

Any Questions?

Thank you!

